



# VCodecV4L2 C++ library

v2.1.2

## Table of contents

- [Overview](#)
- [Versions](#)
- [VCodecV4L2 class description](#)
  - [VCodecV4L2 class declaration](#)
  - [transcode method](#)
  - [setParam method](#)
  - [getParam method](#)
  - [executeCommand method](#)
- [Build and connect to your project](#)
- [Simple example](#)
- [Test application](#)

## Overview

**VCodecV4L2** C++ library provides hardware video **encoding** for H264 and JPEG codecs for **Raspberry Pi 4**. **VCodecV4L2** class inherits interface and data structures from open source [VCodec](#) library and also includes [Logger](#) open source library which provides function for printing logs. **VCodecV4L2** uses [V4L2 API](#). Version 2.1.1 supports only **Raspberry Pi 4** and uses hardware encoders but it is possible to use the library on any other platforms with small changes in code. The library provides simple interface to be implemented in different C++ projects for Raspberry Pi. The library is written with C++17 standard. It is supplied as source code only. The library is a CMake project. Encoding time on **Raspberry PI 4B**, msec:

codec / resolution	1920x1080	1280x720	640x512
H264	12 msec	5.4 msec	2.5 msec
JPEG	25 msec	13 msec	5.5 msec

Encoding time on **Raspberry Zero W2**, msec:

codec / resolution	1920x1080	1280x720	640x512
H264	19.5 msec	8.7 msec	2.8 msec
JPEG	33.4 msec	15.7 msec	5.1 msec

## Versions

**Table 1** - Library versions.

Version	Release date	What's new
1.0.0	29.06.2023	First version.
2.0.0	02.08.2023	- Interface changes to <a href="#">VCodec</a> . - Added JPEG encoding support. - Test application updated.
2.0.1	21.08.2023	- Bug fixed in transcode on copy constructor of dst frame.
2.1.0	28.08.2023	- YUYV input pixel format changed to NV12 for H264 and JPEG codecs. - Added example application.
2.1.1	20.11.2023	- BGR565 conversion is fixed for JPEG encoding.
2.1.2	10.01.2024	- Submodules updated. - Documentation updated. - Test application updated.

## Library files

The library is supplied only by source code. The user is given a set of files in the form of a CMake project (repository). The repository structure is shown below:

```

CMakeLists.txt ----- Main CMake file of the library.
3rdparty ----- Folder with third-party libraries.
  CMakeLists.txt ----- CMake file which includes third-party libraries.
  Logger ----- Source code of Logger library.
  VCodec ----- Source code of VCodec interface library.
example ----- Folder with simple example of VCodecV4L2 usage.
  CMakeLists.txt ----- CMake file for example application.
  main.cpp ----- Source code file of example application.
test ----- Folder with codec test application.
  CMakeLists.txt ----- CMake file for codec test application.
  main.cpp ----- Source code file of codec test application.
src ----- Folder with source code of the library.
  CMakeLists.txt ----- CMake file of the library.
  VCodecV4L2.cpp ----- Source code file of the library.
  VCodecV4L2.h ----- Header file which includes VCodecV4L2 class declaration.
  VCodecV4L2Version.h ----- Header file which includes version of the library.

```

# VCodecV4L2 class description

---

## VCodecV4L2 class declaration

---

**VCodecV4L2** class declared in **VCodecV4L2.h** file. Class declaration:

```
class VCodecV4L2 : public VCodec
{
public:

    /// Get library version.
    static std::string getVersion();

    /// Class constructor.
    VCodecV4L2();

    /// Class destructor.
    ~VCodecV4L2();

    /// Encode video frame.
    bool transcode(Frame& src, Frame& dst);

    /// Set parameter value.
    bool setParam(VCodecParam id, float value);

    /// Get parameter value.
    float getParam(VCodecParam id);

    /// Execute command.
    bool executeCommand(VCodecCommand id);
};
```

## getVersion method

---

**getVersion()** method returns string of current version of **VCodecV4L2** class. Method declaration:

```
static std::string getVersion();
```

Method can be used without **VCodecV4L2** class instance:

```
cout << "VCodecV4L2 class version: " << VCodecV4L2::getVersion() << endl;
```

Console output:

## transcode method

**transcode(...)** method intended to encode and decode video frame ([Frame](#) class). The **VCodecV4L2** library supports only encoding. Video codec encodes/decodes video frames frame-by-frame. Method declaration:

```
bool transcode(Frame& src, Frame& dst);
```

Parameter	Value
src	Source video frame (see <a href="#">Frame</a> class description). To encode video <b>src</b> frame must have raw pixel format <b>NV12</b> .
dst	Result video frame (see <a href="#">Frame</a> class description). To encode video data <b>dst</b> frame must have compressed pixel format (field <b>fourcc</b> of <b>Frame</b> class): <b>JPEG, H264</b> .

**Returns:** TRUE if frame was encoded or FALSE if not.

## setParam method

**setParam(...)** method designed to set new video codec parameters value. Method declaration:

```
setParam(VCodecParam id, float value);
```

Parameter	Description
id	Video codec parameter ID according to <b>VCodecParam</b> enum.
value	Video codec parameter value.

**Returns:** TRUE is the parameter was set or FALSE if not.

**VCodec.h** file of [VCodec](#) library defines IDs for parameters (**VCodecParam** enum) and IDs for commands (**VCodecCommand** enum). **VCodecParam** declaration:

```
enum class VCodecParam
{
    /// [read/write] Log level:
    /// 0-Disable, 1-Console, 2-File, 3-Console and file.
    LOG_LEVEL = 1,
    /// [read/write] Bitrate, kbps. For H264 and H265 codecs.
    BITRATE_KBPS,
    /// [read/write] Quality 0-100%. For JPEG codecs.
    QUALITY,
    /// [read/write] FPS. For H264 and H265 codecs.
    FPS,
    /// [read/write] GOP size. For H264 and H265 codecs.
    GOP,
```

```

    /// [read/write] H264 profile: 0 - Baseline, 1 - Main, 2 - High.
    H264_PROFILE,
    /// [read/write] Codec type. Depends on implementation.
    TYPE,
    /// Custom 1. Depends on implementation.
    CUSTOM_1,
    /// Custom 2. Depends on implementation.
    CUSTOM_2,
    /// Custom 3. Depends on implementation.
    CUSTOM_3
};

```

**Table 2** - Video codec params description. Some params not supported by particular VCodecV4L2 library.

Parameter	Access	Description
LOG_LEVEL	read / write	Logging mode. Valid values: <b>0</b> - Disable. <b>1</b> - Only file. <b>2</b> - Only terminal (console). <b>3</b> - File and terminal.
BITRATE_KBPS	read / write	Bitrate, kbps. For H264 encoding only. According to this value, FPS and GOP size video codec calculate parameter for H264 encoding.
QUALITY	read / write	Quality 0(low quality)-100%(maximum quality). Only for JPEG encoding.
FPS	read / write	FPS. For H264 encoding only. According to this value, FPS and GOP size video codec calculate parameter for H264 encoding.
GOP	read / write	GOP size (Period of key frames) for H264 encoding. Value: 1 - each output frame is key frame, 20 - each 20th frame is key frame etc.
H264_PROFILE	read / write	H264 profile for H264 encoding: 0 - Baseline, 1 - Main, 2 - High.
TYPE	read / write	<b>Not supported</b> by VCodecV4L2 library.
CUSTOM_1	read / write	<b>Not supported</b> by VCodecV4L2 library.
CUSTOM_2	read / write	<b>Not supported</b> by VCodecV4L2 library.
CUSTOM_3	read / write	<b>Not supported</b> by VCodecV4L2 library.

## getParam method

**getParam(...)** method designed to obtain video codec parameter value. Method declaration:

```
float getParam(VCodecParam id);
```

Parameter	Description
id	Video codec parameter ID according to <b>VCodecParam</b> enum (see Table 2).

**Returns:** parameter value or -1 if the parameters not supported.

## executeCommand method

**executeCommand(...)** method designed to execute video codec command. Version 2.0.0 doesn't support commands. Method will return FALSE. Method declaration:

```
bool executeCommand(VCodecCommand id);
```

Parameter	Description
id	Video codec command ID according to <b>VCodecCommand</b> enum.

**Returns:** method returns FALSE in any case.

**VCodec.h** file of [VCodec](#) library defines IDs for parameters (**VCodecParam** enum) and IDs for commands (**VCodecCommand** enum). VCodecCommand declaration:

```
enum class VCodecCommand
{
    /// Reset.
    RESET = 1,
    /// Generate key frame. For H264 and H265 codecs.
    MAKE_KEY_FRAME
};
```

**Table 3** - Video codec commands description. Some commands maybe unsupported by particular video codec class.

Command	Description
RESET	Not supported by VCodecV4L2.
MAKE_KEY_FRAME	Generate next key frame (for H264 encoder). Some hardware may not support this function.

# Build and connect to your project

Install additional software:

```
sudo apt-get -y install build-essential cmake git
```

Typical commands to build **VCodecV4L2** library:

```
cd VCodecV4L2
git submodule update --init --recursive
mkdir build
cd build
cmake ..
make
```

If you want connect **VCodecV4L2** library to your CMake project as source code you can make follow. For example, if your repository has structure:

```
CMakeLists.txt
src
  CMakeList.txt
  yourLib.h
  yourLib.cpp
```

Create folder **3rdparty** in your repository. Copy repository folder **VCodecV4L2** to **3rdparty** folder. New structure of your repository:

```
CMakeLists.txt
src
  CMakeList.txt
  yourLib.h
  yourLib.cpp
3rdparty
  VCodecV4L2
```

Create CMakeLists.txt file in **3rdparty** folder. CMakeLists.txt should contain:

```
cmake_minimum_required(VERSION 3.13)

#####
## 3RD-PARTY
## dependencies for the project
#####
project(3rdparty LANGUAGES CXX)

#####
## SETTINGS
## basic 3rd-party settings before use
#####
# To inherit the top-level architecture when the project is used as a submodule.
```

```

SET(PARENT ${PARENT}_YOUR_PROJECT_3RDPARTY)
# Disable self-overwriting of parameters inside included subdirectories.
SET(${PARENT}_SUBMODULE_CACHE_OVERWRITE OFF CACHE BOOL "" FORCE)

#####
## CONFIGURATION
## 3rd-party submodules configuration
#####
SET(${PARENT}_SUBMODULE_VCODEC_V4L2 ON CACHE BOOL "" FORCE)
if (${PARENT}_SUBMODULE_VCODEC_V4L2)
    SET(${PARENT}_VCODEC_V4L2 ON CACHE BOOL "" FORCE)
    SET(${PARENT}_VCODEC_V4L2_TEST OFF CACHE BOOL "" FORCE)
    SET(${PARENT}_VCODEC_V4L2_EXAMPLE OFF CACHE BOOL "" FORCE)
endif()

#####
## INCLUDING SUBDIRECTORIES
## Adding subdirectories according to the 3rd-party configuration
#####
if (${PARENT}_SUBMODULE_VCODEC_V4L2)
    add_subdirectory(VCodecV4L2)
endif()

```

File **3rdparty/CMakeLists.txt** adds folder **VCodecV4L2** to your project and will exclude test application from compiling. Your repository new structure will be:

```

CMakeLists.txt
src
  CMakeList.txt
  yourLib.h
  yourLib.cpp
3rdparty
  CMakeLists.txt
  VCodecV4L2

```

Next you need include folder 3rdparty in main **CMakeLists.txt** file of your repository. Add string at the end of your main **CMakeLists.txt**:

```
add_subdirectory(3rdparty)
```

Next you have to include VCodecV4L2 library in your **src/CMakeLists.txt** file:

```
target_link_libraries(${PROJECT_NAME} VCodecV4L2)
```

Done!



# Simple example

Example application generates image colour pattern with moving rectangle and writes compressed data to binary file "out.h264". Example shows how to create codec objects and how to encode video frames:

```
#include <iostream>
#include "VCodecV4L2.h"

int main(void)
{
    // Create codec and set params.
    cr::video::VCodec* videoCodec = new cr::video::VCodecV4L2();
    videoCodec->setParam(cr::video::VCodecParam::BITRATE_KBPS, 2500);
    videoCodec->setParam(cr::video::VCodecParam::GOP, 30);
    videoCodec->setParam(cr::video::VCodecParam::FPS, 30);
    videoCodec->setParam(cr::video::VCodecParam::H264_PROFILE, 0);

    // Create NV12 frame and fill color plane by random values.
    const int width = 1280;
    const int height = 720;
    cr::video::Frame frameNv12(width, height, cr::video::Fourcc::NV12);
    for (uint32_t i = 0; i < frameNv12.size; ++i)
        frameNv12.data[i] = (uint8_t)i;

    // Create output H264 frame.
    cr::video::Frame frameH264(width, height, cr::video::Fourcc::H264);

    // Create output file.
    FILE *outputFile = fopen("out.h264", "w+b");

    // Params for moving object.
    int objectwidth = 128;
    int objectHeight = 128;
    int directionX = 1;
    int directionY = 1;
    int objectX = width / 4;
    int objectY = height / 2;

    // Encode and record 200 frames.
    for (uint8_t n = 0; n < 200; ++n)
    {
        // Draw moving object.
        memset(frameNv12.data, 128, width * height);
        for (int y = objectY; y < objectY + objectHeight; ++y)
            for (int x = objectX; x < objectX + objectHeight; ++x)
                frameNv12.data[y * width + x] = 255;
        objectX += directionX;
        objectY += directionY;
        if (objectX >= width - objectwidth - 5 || objectX <= objectwidth + 5)
            directionX = -directionX;
        if (objectY >= height - objectHeight - 5 || objectY <= objectHeight + 5)
            directionY = -directionY;
    }
}
```

```

// Encode.
if (!videoCodec->transcode(frameNv12, frameH264))
{
    std::cout << "Can't encode frame" << std::endl;
    continue;
}

// Write to file.
fwrite(frameH264.data, frameH264.size, 1, outputFile);
}

// Close file.
fclose(outputFile);

return 1;
}

```

## Test application

Test application (VCodecV4L2/test/main.cpp) for **VCodecV4L2** C++ library shows how library works on **Raspberry PI** platform. Test application generates artificial video, compresses it according to user's parameters (codec type, bitrate or JPEG quality, GOP size and H264 profile) and writes results to binary file "out.h264" or "out.jpeg". To run application perform commands:

```

cd <application folder>
sudo chmod +x VCodecV4L2Test
./VCodecV4L2Test

```

After start you will see output:

```

=====
Video Codec V4L2 for Raspberry PI 4 test
=====

Enter Encoder type (0 - JPEG, 1 - H264) :

```

Chose codec type (0 - JPEG, 1 - H264). If H264 codec chosen you will see message:

```

=====
Video Codec V4L2 for Raspberry PI 4 test
=====

Enter Encoder type (0 - JPEG, 1 - H264) : 1
Default params:
Bitrate, kbps 3000
FPS: 30
GOP size: 30
H264 profile: Baseline
Video width 640
Video height 512
Use default params (0 - no, 1 - yes) :

```

When params chosen test application will create out.h264 file and will record 1000 encoded frames. User can set custom parameters (video resolution, bitrate, GOP size and H264 profile). If JPEG codec chosen you will see message:

```
=====
Video Codec V4L2 for Raspberry PI 4 test
=====

Enter Encoder type (0 - JPEG, 1 - H264) : 1
Default params:
Quality 80
Video width 640
Video height 512
Use default params (0 - no, 1 - yes) :
```

When params chosen test application will encode 1000 frame and will create out.jpeg with compressed last frame. During encoding the application shows encoded data size and encoding time:

```
Output file: out.jpeg
Data size 33457/3110400 time 88.127 msec
Data size 416690/3110400 time 41.159 msec
Data size 420353/3110400 time 34.041 msec
Data size 420908/3110400 time 33.631 msec
Data size 420895/3110400 time 33.205 msec
```